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A NOTE ON THE MATRIX HAFFIAN

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This note contains a transparent presentation of the matrix Haffian. A basic theorem links this matrix and the differential of the matrix function under investigation, viz $\nabla F(X)$ and $dF(X)$.

Frequent use is being made of matrix derivatives as developed by Magnus and Neudecker.

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1. INTRODUCTION

Haff (1981, 1982) introduced a matrix function based on the derivatives of the elements of a **square** matrix function $F(X)$ of a **symmetric** matrix argument X .

We shall name it «the matrix Haffian». It was used by Haff in various multivariate statistical problems.

In this note we shall attempt to give a transparent presentation of the matrix Haffian, and give some applications.

Basic is a differentiable square matrix function $F(X)$, shortly F , which depends on a **symmetric** matrix X . Both matrices have the same dimension. A strategic rôle is being played by a square matrix $\nabla = (d_{ij})$ of differential operators $d_{ij} := 1/2(1 + \delta_{ij})\frac{\partial}{\partial x_{ij}}$, where δ_{ij} is the Kronecker delta ($\delta_{ii} = 1$, $\delta_{ij} = 0$ for $i \neq j$). Haff used the symbol D , and not ∇ . In earlier work on the scalar Haffian (Neudecker 2000) the symbol ∇ was introduced. This was done to avoid confusion with the duplication matrix which was extensively used then. The matrix ∇ will be applied to F and produce ∇F , the matrix Haffian.

In the article frequent use will be made of matrix differentials and derivatives as proposed by Magnus and Neudecker (1999).

2. THE MATRIX HAFFIAN

Consider a differentiable square matrix function $F(X)$ with **symmetric** matrix argument X , both of dimension m . The application of $\nabla = (d_{ij})$, a (square) matrix of differential operators $d_{ij} := 1/2(1 + \delta_{ij})\frac{\partial}{\partial x_{ij}}$ to F yields ∇F . Its ik^{th} typical element is

$$\sum_j d_{ij} f_{jk} = 1/2 \sum_j (1 + \delta_{ij}) \frac{\partial f_{jk}}{\partial x_{ij}} = \frac{\partial f_{ik}}{\partial x_{ii}} + 1/2 \sum_{i \neq j} \frac{\partial f_{jk}}{\partial x_{ij}}.$$

We shall prove a basic result.

Theorem

When $dF = P(dX)Q'$, then $\nabla F = 1/2P'Q' + 1/2(\text{tr}P)Q'$.

Proof

Using

$$dX = \Sigma_{ij}(dx_{ij})E_{ij},$$

where

$$X = \Sigma_{ij}x_{ij}E_{ij}$$

and E_{ij} is the ij^{th} basis matrix, we get

$$\begin{aligned} dF &= P(dX)Q' = \Sigma_{ij}(dx_{ij})PE_{ij}Q' = \\ &= \Sigma_i(dx_{ii})PE_{ii}Q' + \sum_{i \neq j}(dx_{ij})PE_{ij}Q'. \quad (i, j = 1 \dots m) \end{aligned}$$

Hence

$$(1) \quad \frac{\partial F}{\partial x_{ii}} = PE_{ii}Q'$$

$$(2) \quad \frac{\partial F}{\partial x_{ij}} = P(E_{ij} + E_{ji})Q'. \quad (i \neq j)$$

The second expression follows from the symmetry of X , where $x_{ij} = x_{ji}$ ($i \neq j$).

Consider the ik^{th} typical element of ∇F , viz

$$\begin{aligned} \Sigma_j d_{ij} f_{jk} &= \frac{\partial f_{ik}}{\partial x_{ii}} + 1/2 \sum_{j \neq i} \frac{\partial f_{jk}}{\partial x_{ij}} \\ &= e'_i \frac{\partial F}{\partial x_{ii}} e_k + 1/2 \sum_{j \neq i} e'_j \frac{\partial F}{\partial x_{ij}} e_k \\ &= e'_i P E_{ii} Q' e_k + 1/2 \sum_{j \neq i} e'_j P (E_{ij} + E_{ji}) Q' e_k \\ &= e'_i P e_i e'_i Q' e_k + 1/2 \sum_{j \neq i} e'_j P (e_i e'_j + e_j e'_i) Q' e_k \\ &= p_{ii} q_{ki} + 1/2 \sum_{j \neq i} (p_{ji} q_{kj} + p_{jj} q_{ki}) \\ &= 1/2 \sum_j p_{ji} q_{kj} + 1/2 \sum_j p_{jj} q_{ki} \\ &= 1/2 (QP)_{ki} + 1/2 (\text{tr}P) q_{ki} \\ &= 1/2 (P' Q')_{ik} + 1/2 (\text{tr}P) (Q')_{ik}. \end{aligned}$$

Hence $(\nabla F)_{ik} = 1/2[P'Q' + (\text{tr}P)Q']_{ik}$,

$$\nabla F = 1/2P'Q' + 1/2(\text{tr}P)Q'.$$

We used $E_{ij} = e_i e_j'$, where e_i and e_j are basis vectors. Further $(A)_{ik} = a_{ik} = e_i^T A e_k$ was applied.

□

3. SOME MATRIX HAFFIANS

We consider four matrix Haffians. They are of a simple nature. For one we quote the literature.

$$(1) \quad \nabla P X^{-1} Q' = -1/2 X^{-1} P' X^{-1} Q' - 1/2(\text{tr} P X^{-1}) X^{-1} Q'.$$

Proof

Now

$$dF = dP X^{-1} Q' = P(dX^{-1})Q' = -P X^{-1}(dX)X^{-1}Q',$$

by virtue of $dX^{-1} = -X^{-1}(dX)X^{-1}$.

Using the Theorem with the substitutions $P \rightarrow -P X^{-1}$ and $Q' \rightarrow X^{-1}Q'$ we get the result immediately.

□

Note. Haff (1982, Lemma 6i) gave $\nabla Q X^{-1}$ by using a long-winded procedure. We have $\nabla Q X^{-1} = -1/2 X^{-1} Q' X^{-1} - 1/2(\text{tr} Q X^{-1}) X^{-1}$.

$$(2) \quad \nabla P X Q X R' = 1/2 P' Q X R' + 1/2(\text{tr} P) Q X R' + 1/2 Q' X P' R' + 1/2(\text{tr} P X Q) R'.$$

Proof

$$dP X Q X R' = P(dX) Q X R' + P X Q(dX) R',$$

which gives the substitutions

$$P \rightarrow P, \quad Q' \rightarrow Q X R' \quad \text{and} \quad P \rightarrow P X Q, \quad Q' \rightarrow R'.$$

The Theorem completes the story.

□

$$(3) \quad \nabla P X^{-2} Q' = -1/2 X^{-1} P' X^{-2} Q' - 1/2(\text{tr} P X^{-1}) X^{-2} Q' - 1/2 X^{-2} P' X^{-1} Q' - 1/2(\text{tr} P X^{-2}) X^{-1} Q'.$$

Proof

We have

$$\begin{aligned} dPX^{-2}Q' &= P(dX^{-2})Q' = P(dX^{-1})X^{-1}Q' + PX^{-1}(dX^{-1})Q' \\ &= -PX^{-1}(dX)X^{-2}Q' - PX^{-2}(dX)X^{-2}Q'. \end{aligned}$$

Application of the Theorem with the substitutions $P \rightarrow -PX^{-1}$, $Q' \rightarrow X^{-2}Q'$ and $P \rightarrow -PX^{-2}$, $Q' \rightarrow X^{-1}Q'$ finishes the derivation. \square

$$(4) \quad \begin{aligned} \nabla PX^3Q' &= 1/2P'X^2Q' + 1/2(\text{tr}P)X^2Q' + 1/2XP'XQ' + \\ &\quad + 1/2(\text{tr}PX)XQ' + 1/2X^2P'Q' + 1/2(\text{tr}PX^2)Q'. \end{aligned}$$

Proof

$$dPX^3Q' = P(dX^3)Q = P(dX)X^2Q' + PX(dX)XQ' + PX^2(dX)Q'.$$

There are three sets of substitutions, viz.

$$P \rightarrow P, Q' \rightarrow X^2Q'; P \rightarrow PX, Q' \rightarrow XQ' \text{ and } P \rightarrow PX, Q' \rightarrow Q'.$$

This yields the result. \square

4. SOME REMARKS ON SCALAR HAFFIANS

The scalar Haffian is defined as $\text{tr} \nabla F$.

See Neudecker (2000) for a thorough discussion and some applications. In that article the identity

$$\text{tr} \nabla F = \text{tr} \frac{\partial g}{\partial x'}$$

was established, where $x := v(X)$, $g := v(G)$, $G := 1/2(F + F')$ and $\frac{\partial g}{\partial x'}$ is the Magnus-Neudecker derivative matrix for the vector function $g(x)$.

The scalar Haffian can, of course, immediately be derived from the corresponding matrix Haffian as established in the present article.

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